Algorithms Chapter 25 All-Pairs Shortest Paths

在有向图上算任意 2 卓的最短距

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Outline

Shortest paths and matrix multiplication

- The Floyd-Warshall algorithm
- Johnson's algorithm for sparse graphs

用矩陣乘法算任意 2 卓的最短距 => O (n³lgn) Floyd-Warshall 演算法 => O (n³) }=者都是 dynamic- programing

Overview_{1/2}

- Input: A weighted directed graph G = (V, E).
- **Output:** An $n \times n$ matrix of shortest-path distances $\delta(u,v)$.
- Could run Bellman-Ford
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 - $O(n^2m)$ which is $O(n^4)$ if the graph is **dense** ($E = \Theta(n^2)$).
- If no negative-weight edges, could run Dijkstra's algorithm algorithm once from each vertex:
 - $O(nm \lg n)$ with binary heap $-O(n^3 \lg n)$ if dense.
 - $O(n^2 \lg n + nm)$ with Fibonacci heap $O(n^3)$ if dense.

Overview_{2/2}

Input: The adjacency matrix W of a weighted directed graph G = (V, E), where

$$w_{ij} = \begin{cases} 0 & \text{if } i = j, \\ \text{the weight of edge } (i, j) & \text{if } i \neq j \text{ and } (i, j) \in E, \\ \infty & \text{if } i \neq j \text{ and } (i, j) \notin E. \end{cases}$$

Negative weights – "allow". Negative-weight cycles – "no".
 negative - weight edge : 3

Output: A matrix D = (d_{ij}), where d_{ij} = δ(i, j).
 D: 目前最短距

假設台北到高雄最短距離經过台中 台北到高雄最短距=台北到台中最短距+台中到高雄最短距 Shortest paths and matrix multiplication

- A dynamic programming approach
- Optimal substructure: subpaths of shortest paths are shortest paths. 問題的最佳解包含子問題的最佳解
- ▶ Recursive solution: Let $l_{ij}^{(m)}$ = weight of shortest path from *i* to *j* that contains at most *m* edges. $l_{ij}^{(m)}$; $i \subseteq I_j \subseteq I_j \subseteq I_j \subseteq I_j$
 - m = 0, there is a shortest path from i to j with no edges if and only if i = j.

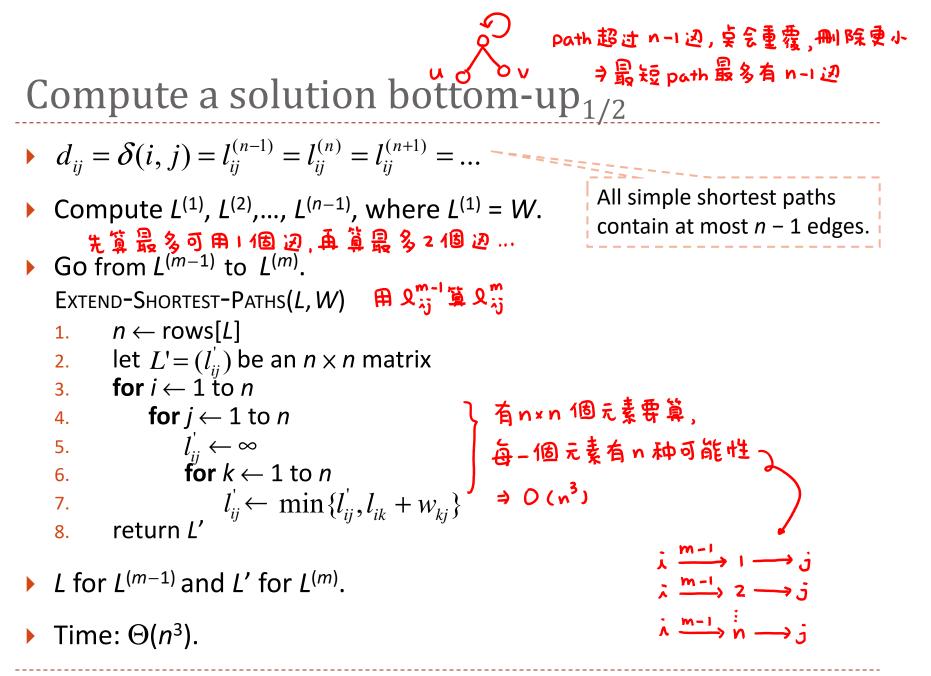
$$l_{ij}^{(0)} = \begin{cases} 0 & \text{if } i = j, \\ \infty & \text{if } i \neq j. \end{cases}$$

$$k_{ij}^{m} = \min \left\{ \sum_{\substack{i=1 \ i \neq j}}^{m-1} \sum_{\substack{i=1 \ i \neq j}}^{m-1} k \rightarrow j \right\}$$

$$m \ge 1, \ l_{ij}^{(m)} = \min \{ l_{ij}^{(m-1)}, \min_{\substack{1 \le k \le n}} \{ l_{ik}^{(m-1)} + w_{kj} \} \}$$

$$= \min_{\substack{1 \le k \le n}} \{ l_{ik}^{(m-1)} + w_{kj} \} \quad (\text{since } w_{ij} = 0).$$

$$m = 1, \text{ we have } \ l_{ii}^{(1)} = w_{ii}. \quad \text{Qat } \mathbf{H} - \mathbf{H}$$



$$L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ 0 & 3 & -5 & 0 & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad L^{(4)} = \begin{pmatrix} 0 & 0 & 3 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad L^{(4)} = \begin{pmatrix} 0 & 0 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

Compute a solution bottom- $up_{2/2}$

• **Observation:** EXTEND is like matrix multiplication: $C = A \cdot B$.

 $L^{(1)} = L^{(0)} \cdot W = W, \quad L^{(2)} = L^{(1)} \cdot W = W^{(2)}, \quad L^{(3)} = L^{(2)} \cdot W = W^{(3)}$ $L^{(n-1)} = L^{(n-2)} \cdot W = W^{(n-1)}.$

• Call EXTEND n-1 times, $D = W^{(n-1)}$ can be computed in $\Theta(n^4)$ time.

$I = \frac{1}{2} \omega^{2}$ $3 = \frac{1}{2} \omega^{8} = \omega^{4} \cdot \omega^{4}$ $I = \frac{1}{2} \omega^{n-1}$ Improving the running time $I = \frac{1}{2} \omega^{2}, \omega^{4}, \omega^{8}, \dots, \omega^{n-1}$ $I = \frac{1}{2} \omega^{2}, \omega^{4}, \omega^{8}, \omega^$

- Only $\lceil \lg(n-1) \rceil$ matrix products is computed.
- Since $2^{\lceil \lg(n-1) \rceil} \ge n-1$, the final product is equal to $W^{(n-1)}$.

FASTER-ALL-PAIRS-SHORTEST-PATHS(W) Time: $\Theta(n^3 \lg n)$

1.
$$n \leftarrow \operatorname{rows}[W]$$

2. $L^{(1)} \leftarrow W$ $\} O(1)$
3. $m \leftarrow 1$
4. while $m < n - 1$
5. $\operatorname{do} L^{(2m)} = \operatorname{Extend-Shortest-Paths}(L^{(m)}, L^{(m)})$ $\} [\lg(n-1)] \cdot \Theta(n^3)$
6. $m \leftarrow 2m$
7. return $L^{(m)}$ $= \operatorname{Extend-Shortest-Paths}(L^{(m)}, L^{(m)})$ $= \operatorname{Extend-Shortest-Paths}(L^{(m)})$ $= \operatorname{Extend-Shorte$

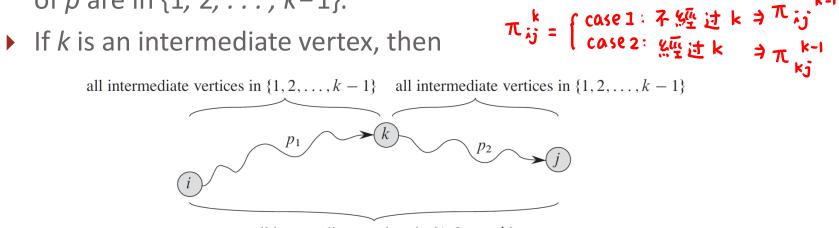
Outline

- ▶ Shortest paths and matrix multiplication }=者都是 dynamic programing
- The Floyd-Warshall algorithm
- Johnson's algorithm for sparse graphs

$d_{ij}^{k} = \min \left\{ \begin{array}{l} case 1 : 孑 經 过 k \Rightarrow d_{ij}^{k-1} \\ case 2 : 照过 k \Rightarrow () \rightarrow () \rightarrow () = d_{ik}^{k-1} + d_{kj} \end{array} \right\}$ Floyd-Warshall algorithm

- A different dynamic-programming approach
- Let d^(k)_{ij} be the weight of a shortest path from i to j with all intermediate vertices in {1, 2, ..., k}. d^k_j: i 到j 只能 經过 編号為 I ~ k 師莫
- Consider a shortest path p from i to j with all intermediate vertices in {1, 2, ..., k}: π片: λ 到 只能 經过 編号為 ι~κ 的桌, j 的 前 個桌

If k is not an intermediate vertex, then all intermediate vertices of p are in {1, 2, ..., k−1}.



$$d_{ij}^{k} = \min \left\{ \begin{array}{l} case1: 孑經过k \Rightarrow d_{ij}^{k-1} \\ case2: 經过k \Rightarrow () \rightarrow () \rightarrow () = d_{ik}^{k-1} + d_{kj} \end{array} \right\}$$

Recursive formulation

A recursive solution:

$$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{if } k = 0, \\ \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}) & \text{if } k \ge 1. \end{cases}$$

- d⁽⁰⁾_{ij} = w_{ij}, because have no intermediate vertices.

 Such a path has ≤ 1 edge. k=0, 不能經过其他莫 d^{ij} = ω_{ij}
- Goal: $D^{(n)} = (d_{ij}^{(n)})$
 - Because for any path, all intermediate vertices are in the set {1, 2,..., n}. 目標: 算点;

Compute bottom up

• Compute the values $d_{ii}^{(k)}$ in order of increasing values of k. FLOYD-WARSHALL(W) $n \leftarrow rows[W]$ 1. - O(1) 2. $D^{(0)} \leftarrow W$ 3. for $k \leftarrow 1$ to nfor $i \leftarrow 1$ to n4. 5. 6. return D(n) 7. • Time: $\Theta(n^3)$. 先算只能經过編号為行的桌

元券:又到了只能經过編号為1~K的桌,了的前一個桌

Constructing a shortest path

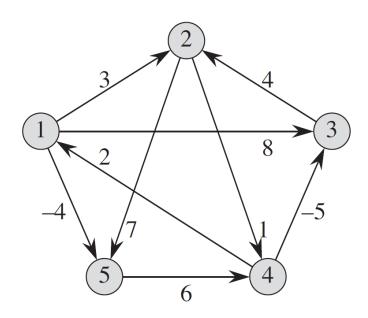
π^(k)_{ij} is the predecessor of vertex j on a shortest path from vertex j with all intermediate vertices in the set {1,2,...,k}.

$$\pi_{ij}^{(0)} = \begin{cases} \text{NIL} & \text{if } i = j, \text{ or } w_{ij} = \infty, & i \Rightarrow j 沒有迥\\ i & \text{if } i \neq j, \text{ and } w_{ij} < \infty. & i \Rightarrow j 有 迥 \end{cases}$$

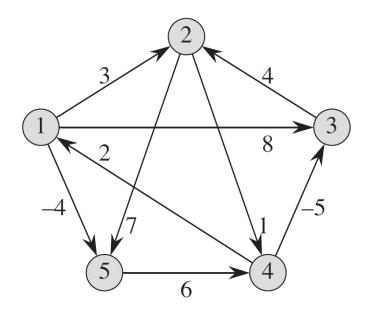
For $k \ge 1$, we have

$$\pi_{ij}^{(k)} = \begin{cases} \pi_{ij}^{(k-1)} & \text{if } d_{ij}^{(k-1)} \le d_{ik}^{(k-1)} + d_{kj}^{(k-1)}, \\ \pi_{kj}^{(k-1)} & \text{if } d_{ij}^{(k-1)} > d_{ik}^{(k-1)} + d_{kj}^{(k-1)}. \end{cases}$$

$$\pi_{ij}^{k} = \begin{cases} case 1 : 不經过k = \pi_{ij}^{k-1} \\ case 2 : 經过k = \pi_{kj}^{k-1} \end{cases}$$



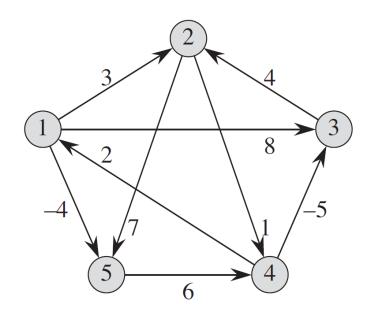
$$D^{(0)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(0)} = \begin{pmatrix} \text{NIL } 1 & 1 & \text{NIL } 1 \\ \text{NIL } \text{NIL } \text{NIL } \text{NIL } 1 \\ 4 & \text{NIL } 4 & \text{NIL } \text{NIL } \text{NIL } \\ \text{NIL } \text{NIL } \text{NIL } \text{NIL } \text{NIL } \text{NIL } \end{pmatrix}$$
$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & (5) & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(1)} = \begin{pmatrix} \text{NIL } 1 & 1 & \text{NIL } 1 \\ \text{NIL } \text{NIL } \text{NIL } \text{NIL } 2 & 2 \\ \text{NIL } 3 & \text{NIL } \text{NIL } 1 \\ \text{NIL } \text{NIL } \text{NIL } 1 & 2 & 2 \\ \text{NIL } 3 & \text{NIL } \text{NIL } 1 \\ \text{NIL } \text{NIL } 1 & 1 & 1 \\ \text{NIL } 1 \\$$



$$d_{42}^{3} = \min \{ 經 过 3, 不經过 3 \}$$

= min { $d_{43}^{2} + d_{32}^{2}, d_{42}^{2} \}$
= min { $-5 + 4, 5^{2} \}$
= -1
 $\pi_{42}^{3} = 經 过 3 \Rightarrow \pi_{32}^{2} \Rightarrow 3$
不經 过 3 $\Rightarrow \pi_{42}^{2} \Rightarrow 1$
有經 过 $\Rightarrow \pi_{42}^{3} = 3$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad \Pi^{(2)} = \begin{pmatrix} \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ 4 & 1 & 4 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$
$$D^{(3)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad \Pi^{(3)} = \begin{pmatrix} \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ \text{NIL} & 1 & 1 & 1 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 \\ \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & 1 \\ \text{$$



$$D^{(4)} = \begin{pmatrix} 0 & 3 & -1 & 4 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad \Pi^{(4)} = \begin{pmatrix} \text{NIL} & 1 & 4 & 2 & 1 \\ 4 & \text{NIL} & 4 & 2 & 1 \\ 4 & 3 & \text{NIL} & 2 & 1 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ 4 & 3 & 4 & 5 & \text{NIL} \end{pmatrix}$$
$$D^{(5)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad \Pi^{(5)} = \begin{pmatrix} \text{NIL} & 3 & 4 & 5 & 1 \\ 4 & \text{NIL} & 4 & 2 & 1 \\ 4 & 3 & \text{NIL} & 2 & 1 \\ 4 & 3 & \text{NIL} & 2 & 1 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ 4 & 3 & 4 & 5 & \text{NIL} \end{pmatrix}$$

遞移性閉包:表示可達性

: O Floyd - Warshall 演算法

Transitive closure_{1/2} ② 使用性贸來節省時間和空間

▶ The transitive closure of G is defined as the graph G* = (V, E*), where (ふうう有辺⇔有 path 可至う)

 $E^* = \{(i, j) : \text{there is a path from vertex } i \text{ to vertex } j \text{ in } G\}.$

• We give two methods to compute the transitive closure of a graph in the following, both in $\Theta(n^3)$ time.

Method 1:

- Assign a weight of 1 to each edge, then run FLOYD-WARSHALL.
- If there is a path from vertex *i* to vertex *j*, we get $d_{ij} < n$.

▶ Otherwise, we get
$$d_{ij} = \infty$$
. 注1: ① 將edge上的weight設為」
② え有 path 到 j ⇔ dzj < n
③ dzj < n ⇔ tzj = 1

只要知道有沒有 path,因此 Transitive closure_{2/2} 法2:使用性贸杂節省時間和空間

Method 2:

- Save time and space in practice. 七点只要存o或o,較節省空間
- Substitute other values and operators in FLOYD-WARSHALL.
 - ▶ min → ∨ (OR) v和 ∧ ,較min 和 + 来的快

▶ +
$$\rightarrow$$
 ∧ (AND)

if there exists a path from i to j with all intermediate 1

$$t_{ij}^{(k)} = \begin{cases} \text{vertices in } \{1, 2, \dots, k\}, \\ 0 \text{ otherwise} \end{cases}$$

0 otherwise.

$$t_{ji}^{(0)} = \begin{cases} 0 & \text{if } i \neq j \text{ and } (i, j) \notin E, \\ 1 & \text{if } i = j \text{ or } (i, j) \in E. \end{cases}$$

$$t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{ki}^{(k-1)}). \quad \stackrel{i \sim k}{\longrightarrow} j = i \xrightarrow{1 \sim k-1} j \stackrel{j \neq k}{\longrightarrow} j \stackrel{j \neq k}{\longrightarrow} (i \xrightarrow{1 \sim k-1} k \not \exists k \xrightarrow{1 \sim k-1} j)$$

Compute bottom up

• Compute the values $t_{ij}^{(k)}$ in order of increasing values of k.

```
TRANSITIVE-CLOSURE(G)

1. n \leftarrow |V[G]| \rightarrow O(1)

2. for i \leftarrow 1 to n

3. for j \leftarrow 1 to n

4. if i = j or (i, j) \in E[G]

5. t_{ij}^{(0)} \leftarrow 1

6. else t_{ij}^{(0)} \leftarrow 0

7. for k \leftarrow 1 to n

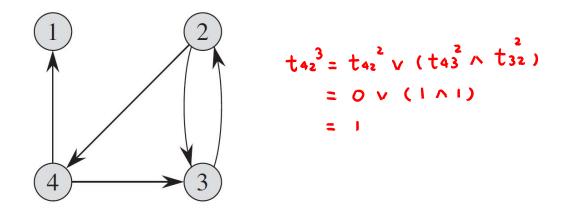
8. for i \leftarrow 1 to n

9. for j \leftarrow 1 to n

10. t_{ij}^{(k)} \leftarrow t_{ij}^{(k-1)} \lor (t_{ik}^{(k-1)} \land t_{kj}^{(k-1)})

11. return T(n)
```

- Time: $\Theta(n^3)$.
- Only 1 bit is required for each $t_{ij}^{(k)}$.
- G* can be used to determine the strongly connected components of G.



$$T^{(0)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad T^{(1)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad T^{(2)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$