# Algorithms Chapter 17 Amortized Analysis

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## Outline

- Aggregate analysis
- ▶ The accounting method
- The potential method
- Dynamic tables

## Amortized analysis

- Analyze a sequence of operations on a data structure.
- ▶ **Goal:** Show that although some individual operations may be expensive, on **average** the cost per operation is small.
  - Average in this context does not mean that we're averaging over a distribution of inputs.
- No probability is involved.
- We're talking about average cost in the worst case.
- We show that for all n, a sequence of n operations takes worst-case time T(n) in total.

## Example 1: Stack operations

- ▶ Stack operations: PUSH(S, x), POP(S), and MULTIPOP(S, k).
- ▶ Push(S, x): push object x onto stack S.
  - $\blacktriangleright$  Each runs in O(1) time.
  - $\blacktriangleright$  A sequence of *n* Push operations takes O(n) time.
- ▶ Pop(S): pop the top of stack S and returns the popped object.
  - Each runs in O(1) time.
  - $\blacktriangleright$  A sequence of n Pop operations takes O(n) time.
- $\blacktriangleright$  MULTIPOP(S,k)
  - 1. while not STACK-EMPTY(S) and k > 0
  - Pop(S)
  - 3.  $k \leftarrow k-1$

## Running time analysis<sub>1/2</sub>

- Running time of MULTIPOP(S,k):
  - ▶ Let each PUSH/POP cost O(1).
  - The number of iterations of while loop is min(s, k), where s = number of objects on stack.
  - ▶ Therefore, total cost = min(s, k).
- ▶ The running time of a sequence of *n* PUSH, POP, MULTIPOP operations?
- Analysis(I):
  - Worst-case cost of Multipop is O(n).
  - ▶ Have *n* operations.
  - ▶ Therefore, worst-case cost of sequence is  $O(n^2)$ .

## Running time analysis<sub>2/2</sub>

#### Analysis(II):

- ▶ Each object can be popped only once per time that it's pushed.
- ▶ At most *n* objects are pushed into *S*.
- ▶ Have  $\leq n$  Pushes  $\Rightarrow \leq n$  Pops, including those in Multipop.
- ▶ Therefore, total cost = O(n).
- Average cost of an operation = O(1).
- ▶ Emphasize again, no probabilistic reasoning was involved.
  - $\blacktriangleright$  Showed worst-case O(n) cost for sequence.
  - $\blacktriangleright$  Therefore, O(1) per operation on average.

## Example 2: Incrementing a binary counter

- k-bit binary counter A[0..k-1] of bits
  - ▶ A[0] is the least significant bit.
  - ▶ A[k-1] is the most significant bit.
  - Value of counter is  $\sum_{i=0}^{k-1} A[i] \cdot 2^i$ .
- Initially, counter value is 0.
- ▶ To add 1 (modulo  $2^k$ ), we use the following procedure.

```
INCREMENT(A)

1. i \leftarrow 0

2. while i < k and A[i] = 1

3. A[i] \leftarrow 0

4. i \leftarrow i + 1

5. if i < k

6. then A[i] \leftarrow 1
```

```
Counter
                           Total
value
                           cost
       0 0 0 0 0 1
                            10
                            11
       0 0 0 0 1 0 0
       0 0 0 0 1 0
                           16
       0 0 0 0 1 0 1 0
                            18
                            19
        0 0 0 0 1 1 0 0
                           22
 13
        0 0 0 0 1 1 0 1
                           23
        0 0 0 0 1 1 1 0
                           25
                           26
 16
        0 0 0 1 0 0 0 0
                            31
```

## Running time analysis

▶ The running time of a sequence of *n* INCREMENT operations?

## Analysis(I):

- $\blacktriangleright$  A single execution of INCREMENT takes time O(k) in the worst case.
- ▶ Have *n* operations.
- $\blacktriangleright$  Therefore, worst-case cost of sequence is O(nK).
- Average cost of an operation = O(k).

## Analysis(II):

- ▶ A[0] flips every time, A[1] flips only every other time, A[2] flips only every fourth time, and so on.
- ► Total number of flips is  $T(n) = n + \lfloor n/2 \rfloor + \lfloor n/4 \rfloor + ...$  $\leq 2n$
- Average cost of an operation = O(1).

## Outline

- Aggregate analysis
- ▶ The accounting method
- The potential method
- Dynamic tables

# The accounting method $_{1/2}$

- Assign different charges to different operations.
  - Some are charged more than actual cost.
  - Some are charged less.
- ▶ The amount we charge an operation is called its amortized cost.
- When amortized cost > actual cost, store (amortized cost actual cost) on specific objects in the data structure as credit.
- Use credit later to pay for operations whose actual cost > amortized cost.
- Differs from aggregate analysis:
  - In the accounting method, different operations can have different costs.
  - ▶ In aggregate analysis, all operations have same cost.

## The accounting method $_{2/2}$

- Need credit to never go negative.
  - Otherwise, have a sequence of operations for which the amortized cost is not an upper bound on actual cost.
  - Amortized cost would tell us nothing.
- Let  $c_i$  = actual cost of *i*th operation,  $\hat{c}_i$  = amortized cost of *i*th operation.
- ▶ Then require  $\sum_{i=1}^{n} \hat{c}_i \ge \sum_{i=1}^{n} c_i$  for all sequences of n operations.
- Total credit stored in the data structure =  $\sum_{i=1}^{n} \hat{c}_i \sum_{i=1}^{n} c_i$ .

## Example 1: Stack operations

operation	actual cost	amortized cost
Push	1	2
Рор	1	0
MULTIPOP	min( <i>k, s</i> )	0

- Intuition: When pushing an object, pay 2.
  - ▶ \$1 pays for the Push.
  - ▶ \$1 is prepayment for it being popped by either POP or MULTIPOP.
  - Since each object has \$1, which is credit, the credit ≥ 0.
  - ▶ Therefore, total amortized cost  $\leq 2n$ , is an upper bound on total actual cost.
  - Average cost of an operation = O(1).

## Example 2: Incrementing a binary counter

## ▶ Charge \$2 to set a bit to 1.

- ▶ \$1 pays for setting a bit to 1.
- ▶ \$1 is prepayment for flipping it back to 0.
- ▶ Have \$1 of credit for every 1 in the counter.
- ▶ Therefore, credit  $\geq$  0.

#### Amortized cost of INCREMENT:

- Cost of resetting bits to 0 is paid by credit.
- ▶ At most 1 bit is set to 1.
- Therefore, amortized cost ≤ \$2.
- For *n* operations, amortized cost = O(n).
- Average cost of an operation = O(1).

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- ▶ The potential method
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## The Potential method<sub>1/2</sub>

- Like the accounting method, but think of the credit as **potential** stored with the **entire data structure**.
  - Can release potential to pay for future operations.
  - Most flexible of the amortized analysis methods.
- Let  $D_i$  = data structure after *i*th operation,  $D_0$  = initial data structure,  $c_i$  = actual cost of *i*th operation,  $\hat{c}_i$  = amortized cost of *i*th operation.
- ▶ Potential function  $\Phi: D_i \to R$ 
  - $\Phi(D_i)$  is the potential associated with data structure  $D_i$ .

$$\hat{c}_i = c_i + \Phi(D_i) - \Phi(D_{i-1})$$

increase in potential due to ith operation

## The Potential method<sub>2/2</sub>

$$\begin{aligned} & \text{Total amortized cost} = \sum_{i=1}^{n} \hat{c}_{i} \\ & = \sum_{i=1}^{n} (c_{i} + \Phi(D_{i}) - \Phi(D_{i-1})) \\ & = \sum_{i=1}^{n} c_{i} + \Phi(D_{n}) - \Phi(D_{0}). \end{aligned}$$

- If we require that  $\Phi(D_i) \ge \Phi(D_0)$  for all i, then the amortized cost is always an upper bound on actual cost.
- ▶ In practice:  $\Phi(D_0) = 0$ ,  $\Phi(D_i) \ge 0$  for all i.

## Example 1: Stack operations

- $\Phi$  = # of objects in stack.
- $D_0 = \text{empty stack} \Rightarrow \Phi(D_0) = 0.$
- ▶ Since # of objects in stack  $\geq 0$ ,  $\Phi(D_i) \geq 0 = \Phi(D_0)$  for all i.

operation	actual cost	$\Phi(D_i) - \Phi(D_{i-1})$	amortized cost	
PUSH	1	(s+1)-s=1	1 + 1 = 2	
Рор	1	(s-1)-s=-1	1 - 1 = 0	
MULTIPOP	$k' = \min(k, s)$	(s-k')-s=-k'	k'-k'=0	
s = # of objects initially.				

▶ Therefore, amortized cost of a sequence of *n* operations

$$=\sum_{i=1}^n \hat{c}_i = O(n).$$

# Example 2: Incrementing a binary counter<sub>1/2</sub>

- $\Phi = b_i = \#$  of 1's after *i*th INCREMENT.
- ▶  $D_0$  = all bits are set to zero  $\Rightarrow \Phi(D_0) = 0$ .
- $\blacktriangleright$  Suppose *i*th operation resets  $t_i$  bits to 0.
  - ▶  $c_i \le t_i + 1$ . (resets  $t_i$  bits, sets at most one bit to 1)
  - If  $b_i = 0$ , the *i*th operation reset all *k* bits and didn't set one, so  $b_{i-1} = t_i = k \Rightarrow b_i = b_{i-1} t_i$ .
  - If  $b_i > 0$ , the *i*th operation reset  $t_i$  bits, set one, so  $b_i = b_{i-1} t_i + 1$ .
  - ► In either case,  $b_i \le b_{i-1} t_i + 1$ .

# Example 2: Incrementing a binary counter<sub>2/2</sub>

- Therefore,  $\Phi(D_i) \Phi(D_{i-1}) = b_i b_{i-1}$   $\leq (b_{i-1} - t_i + 1) - b_{i-1}$  $= 1 - t_i$ .
- The amortized cost is therefore  $\hat{c}_i = c_i + \Phi(D_i) \Phi(D_{i-1})$   $\leq (t_i + 1) + (1 - t_i)$ = 2.
- Thus, amortized cost of n operations =  $\sum_{i=1}^{n} \hat{c}_i = O(n)$ .

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## Dynamic tables<sub>1/2</sub>

#### Scenario

- ▶ Have a table maybe a hash table.
- Don't know in advance how many objects will be stored in it.
- ▶ When it fills, must reallocate with a larger size, copying all objects into the new, larger table.
- When it gets sufficiently small, might want to reallocate with a smaller size.
- ▶ Initially, *T* is a table of size 0.
- Perform a sequence of n operations on T, each of which is either Insert or Delete.

#### Goals

- $\triangleright$  O(1) amortized time per operation.
- ▶ Unused space always ≤ constant fraction of allocated space.

# Dynamic tables<sub>2/2</sub>

## $\blacktriangleright$ Load factor $\alpha(T)$

- $\qquad \alpha(T) = \text{num}[T]/\text{size}[T]$ 
  - ▶ num[T] = # items stored, size[T] = allocated size.
- If size[T] = 0, then num[T] = 0. Define  $\alpha$  = 1.
- Never allow  $\alpha > 1$ .
- Keep  $\alpha$  > a constant fraction.

## Table expansion

```
TABLE-INSERT (T, x)
      if size [T] = 0
           then allocate table[T] with 1 slot
2.
                  size[T] \leftarrow 1
3.
      if num[T] = size[T]
           then allocate new-table with 2 \cdot \text{size}[T] slots
5.
                  insert all items in table[T] into new-table
                  free table[T]
7.
                  table[T] \leftarrow new-table
                  size[T] \leftarrow 2 \cdot size[T]
9.
      insert x into table[T]
      num[T] \leftarrow num[T] + 1
11.
```

Notice: If only insertions are performed, the load factor of a table is always at least 1/2.

- When the table becomes full, double its size and reinsert all existing items.
- ► Each time we actually insert an item into the table, it's an elementary insertion.

## Running time analysis

▶ The running time of a sequence of n TABLE-INSERT operations on an initially empty table ?

## Analysis(I):

- $ightharpoonup c_i$  = actual cost of *i*th operation.
- If not full,  $c_i = 1$ .
- ▶ If full, have i-1 items in the table at the start of the *i*th operation. Have to copy all i-1 existing items, then insert *i*th item  $\Rightarrow c_i = i$ .
- ▶ *n* operations  $\Rightarrow c_i = O(n) \Rightarrow O(n^2)$  time for *n* operations.

## Aggregate analysis

## Analysis(II):

 $\blacktriangleright$  Expand only when i-1 is an exact power of 2.

$$c_i = \begin{cases} i & \text{if } i-1 \text{ is exact power of } 2, \\ 1 & \text{otherwise.} \end{cases}$$

Totol cost = 
$$\sum_{i=1}^{n} c_{i} \leq n + \sum_{j=0}^{\lfloor \lg n \rfloor} 2^{j}$$

$$= n + \frac{2^{\lfloor \lg n \rfloor + 1} - 1}{2 - 1}$$

$$< n + 2n$$

$$= 3n$$

▶ Therefore, **aggregate analysis** says amortized cost per operation = 3.

## Accounting method

- Charge \$3 per insertion of x.
  - ▶ \$1 pays for x's insertion.
  - ▶ \$1 pays for *x* to be moved in the future.
  - ▶ \$1 pays for some other item to be moved.
- Suppose that the size of the table is m immediately after an expansion.
  - Assume that the expansion used up all the credit, so that there's no credit stored after the expansion.
  - Will expand again after another m insertions.
  - ▶ Each insertion will put \$1 on one of the *m* items that were in the table just after expansion and will put \$1 on the item inserted.
  - ▶ Have \$2*m* of credit by next expansion, when there are 2*m* items to move. Enough to pay for the expansion, with no credit left over!

## Potential method<sub>1/3</sub>

- $\Phi(T) = 2 \cdot \text{num}[T] \text{size}[T]$ 
  - Initially, num[T] = size[T] =  $0 \Rightarrow \Phi(T) = 0$ .
  - ▶ Just after expansion, size[T] =  $2 \cdot \text{num}[T] \Rightarrow \Phi(T) = 0$ .
  - ▶ Just before expansion, size[T] = num[T]  $\Rightarrow \Phi(T)$  = num[T]  $\Rightarrow$  have enough potential to pay for moving all items.
  - Always have  $\Phi(T) \ge 0$ .  $\operatorname{num}[T] \ge 1/2 \cdot \operatorname{size}[T]$   $\Rightarrow 2 \cdot \operatorname{num}[T] \ge \operatorname{size}[T]$  $\Rightarrow \Phi(T) \ge 0$ .

#### Amortized cost of ith operation:

```
num_i = num[T] after ith operation,

size_i = size[T] after ith operation ,

\Phi_i = \Phi after ith operation.
```

## Potential method<sub>2/3</sub>

#### If no expansion:

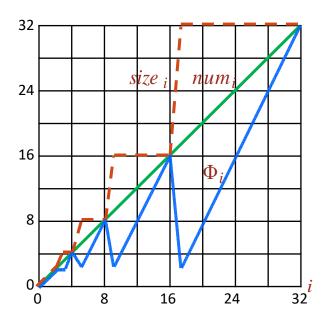
$$size_i = size_{i-1},$$
  
 $num_i = num_{i-1} + 1,$   
 $c_i = 1.$ 

$$\hat{c}_{i} = c_{i} + \Phi_{i} - \Phi_{i-1} 
= 1 + (2 \cdot num_{i} - size_{i}) - (2 \cdot num_{i-1} - size_{i-1}) 
= 1 + (2 \cdot num_{i} - size_{i}) - (2(num_{i} - 1) - size_{i}) 
= 1 + 2 
= 3.$$

#### If expansion:

$$\begin{aligned} size_{i} &= 2 \cdot size_{i-1}, \\ size_{i-1} &= num_{i-1} = num_{i} - 1, \\ c_{i} &= num_{i-1} + 1 = num_{i}. \\ \hat{c}_{i} &= c_{i} + \Phi_{i} - \Phi_{i-1} \\ &= num_{i} + \left(2 \cdot num_{i} - size_{i}\right) - \left(2 \cdot num_{i-1} - size_{i-1}\right) \\ &= num_{i} + \left(2 \cdot num_{i} - 2\left(num_{i} - 1\right)\right) - \left(2\left(num_{i} - 1\right) - \left(num_{i} - 1\right)\right) \\ &= num_{i} + 2 - \left(num_{i} - 1\right) \end{aligned}$$

# Potential method<sub>3/3</sub>



- ▶ The above Figure plots the values of  $num_i$ ,  $size_i$ , and  $\Phi_i$  against i.
- Notice how the potential builds to pay for the expansion of the table.

## Expansion and contraction<sub>1/2</sub>

- When  $\alpha$  drops too low, contract the table.
  - Allocate a new, smaller one.
  - Copy all items.

#### Preserve two properties

- $\blacktriangleright$  load factor  $\alpha$  bounded below by a positive constant, and
- amortized cost per operation bounded above by a constant.

#### Obvious strategy

- Double size when inserting into a full table.
- Halve size when deletion would make table less than half full.
- ▶ Then always have  $1/2 \le \alpha \le 1$ .

## Expansion and contraction<sub>2/2</sub>

## Consider the following scenario

halve

- ▶ The first n/2 operations are insertions,
- For the second n/2 operations, we perform the following sequence: insert, delete, delete, insert, insert, delete, insert, insert,...

halve

double

▶ The cost of each expansion and contraction is  $\Theta(n)$ .

double

▶ The total cost of the *n* operations is  $\Theta(n^2)$ .

#### Simple solution:

double

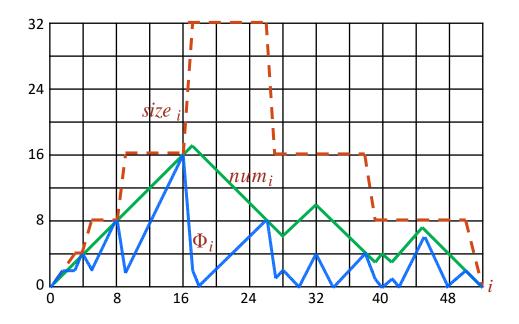
- Double size when inserting into a full table.
- ▶ Halve size when deleting from a 1/4 full table.
- After either expansion or contraction,  $\alpha = 1/2$ .
- ▶ Always have  $1/4 \le \alpha \le 1$ .

# Some properties<sub>1/3</sub>

#### Observation 1:

- Need to delete half the items before contraction.
- Need to double number of items before expansion.
- Let  $\Phi(T) = \begin{cases} 2 \cdot num[T] size[T] & \text{if } \alpha \ge 1/2, \\ size[T]/2 num[T] & \text{if } \alpha < 1/2. \end{cases}$ 
  - $T \text{ empty} \Rightarrow \Phi = 0$ .
  - ▶  $\alpha \ge 1/2 \Rightarrow \text{num} \ge 1/2 \cdot \text{size} \Rightarrow 2 \cdot \text{num} \ge \text{size} \Rightarrow \Phi \ge 0$ .
  - ▶  $\alpha < 1/2 \Rightarrow \text{num} < 1/2 \cdot \text{size} \Rightarrow \Phi \ge 0$ .

# Some properties<sub>2/3</sub>



▶ The potential is never negative. Thus, the total amortized cost of a sequence of operations with respect to  $\Phi$  is an upper bound on the actual cost of the sequence.

## Some properties<sub>3/3</sub>

#### Observation 2:

- $\alpha = 1/2 \Rightarrow \Phi = 2 \cdot \text{num} 2 \cdot \text{num} = 0.$
- $\alpha = 1 \Rightarrow \Phi = 2 \cdot \text{num} \text{num} = \text{num}$
- $\alpha = 1/4 \Rightarrow \Phi = \text{size}/2 \text{num} = 4 \cdot \text{num}/2 \text{num} = \text{num}$
- ▶ Therefore, when we double or halve, have enough potential to pay for moving all num items.
- Let  $c_i$  = actual cost of ith operation,  $\hat{c}_i$  = amortized cost of ith operation,  $num_i$  = the number of items after the ith operation,  $size_i$  = the size of the table after the ith operation,  $\alpha_i$  = the load factor of the table after the ith operation,  $\Phi_i$  = the potential after the ith operation.

## Analysis: insert operation<sub>1/2</sub>

- ► Case 1:  $α_{i-1} ≥ 1/2$ 
  - ▶ The same analysis as before.
  - The amortized cost  $\hat{c}_i = 3$ .
- ► Case 2:  $\alpha_{i-1}$  < 1/2 and  $\alpha_i$  < 1/2 (no expansion)

```
\hat{c}_{i} = c_{i} + \Phi_{i} + \Phi_{i-1} 

= 1 + (size_{i} / 2 - num_{i}) - (size_{i-1} / 2 - num_{i-1}) 

= 1 + (size_{i} / 2 - num_{i}) - (size_{i} / 2 - (num_{i} - 1)) 

= 0.
```

## Analysis: insert operation<sub>2/2</sub>

► Case 3:  $\alpha_{i-1} < 1/2$  and  $\alpha_i \ge 1/2$  (no expansion)

$$\hat{c}_{i} = 1 + (2 \cdot num_{i} - size_{i}) - (size_{i-1} / 2 - num_{i-1}) 
= 1 + (2 (num_{i-1} + 1) - size_{i-1}) - (size_{i-1} / 2 - num_{i-1}) 
= 3 \cdot num_{i-1} - \frac{3}{2} \cdot size_{i-1} + 3 
= 3 \cdot \alpha_{i-1} size_{i-1} - \frac{3}{2} \cdot size_{i-1} + 3 
< \frac{3}{2} \cdot size_{i-1} - \frac{3}{2} \cdot size_{i-1} + 3 
= 3.$$

▶ Therefore, amortized cost of insert is at most 3.

## Analysis: delete operation $_{1/3}$

- Case 1:  $\alpha_{i-1} < 1/2$ 
  - ▶ This implies  $\alpha_i$  < 1/2.
  - If no contraction:

$$\hat{c}_{i} = 1 + (size_{i} / 2 - num_{i}) - (size_{i-1} / 2 - num_{i-1}) 
= 1 + (size_{i} / 2 - num_{i}) - (size_{i} / 2 - (num_{i} + 1)) 
= 2.$$

If contraction:

```
\hat{c}_{i} = \underbrace{(num_{i}+1) + (size_{i}/2 - num_{i}) - (size_{i-1}/2 - num_{i-1})}_{\text{move} + \text{delete}}
\underbrace{[size_{i}/2 = size_{i-1}/4 = num_{i-1} = num_{i} + 1]}_{\text{e}} = \underbrace{(num_{i}+1) + ((num_{i}+1) - num_{i}) - ((2 \cdot num_{i}+2) - (num_{i}+1))}_{\text{e}}
= 1.
```

## Analysis: delete operation $_{1/2}$

- ► Case 2:  $\alpha_{i-1} \ge 1/2$  (No contraction happens)
  - ► Case 2a:  $\alpha_i \ge 1/2$ :

$$\hat{c}_{i} = 1 + (2 \cdot num_{i} - size_{i}) - (2 \cdot num_{i-1} - size_{i-1}) 
= 1 + (2 \cdot num_{i} - size_{i}) - (2 \cdot num_{i} + 2 - size_{i}) 
= -1.$$

• Case 2b:  $\alpha_i < 1/2$ :

Since  $\alpha_{i-1} \ge 1/2$ , we have

$$num_i = num_{i-1} - 1 \ge \frac{1}{2} \cdot size_{i-1} - 1 = \frac{1}{2} \cdot size_i - 1.$$

Thus, 
$$\hat{c}_{i} = 1 + (size_{i}/2 - num_{i}) - (2 \cdot num_{i-1} - size_{i-1})$$
  
 $= 1 + (size_{i}/2 - num_{i}) - (2 \cdot num_{i-1} - size_{i})$   
 $= -1 + \frac{3}{2} \cdot size_{i-1} - 3 \cdot num_{i}$   
 $\leq -1 + \frac{3}{2} \cdot size_{i-1} - 3 \left(\frac{1}{2} \cdot size_{i-1} - 1\right)$ 

## Summary

- ▶ Therefore, amortized cost of delete is at most 2.
- The amortized cost of each operation is bounded above by a constant.
- The actual time for any sequence of n operations on a dynamic table is O(n).

#### Insertion Only ( $\alpha \ge 1/2$ )

#### Delection Only ( $\alpha \le 1/2$ )

